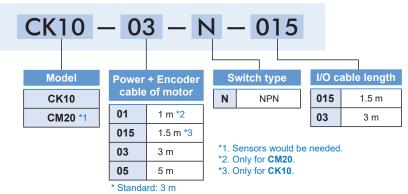
CK10 / CM20 series



ELECTRIC CYLINDER CONTROLLER

Controller model	Туре	Specification	Exterior	Features
CK10 Torque type	 RS-485 serial communication I/O Pulse input 	24VDC±10% max. 500mA (Except motor current)		 Support RS-485 communication (Modbus RTU) Support single / double pulse control Support Position Table motion control function Offer Dynamic-link library for PC Base(.dll for C++, C#) Support torque control with interrupt / continue function
CM20 Position type			Marine Contraction	 Support RS-485 communication (Modbus RTU) Support single / double pulse control Programmable motion control function

Order example of controller



Accessories

Order example		Description				
CK10	-ME015	Power + Encoder cable of motor - 1.5 m				
	-ME03	Power + Encoder cable of motor - 3 m				
	-ME05	Power + Encoder cable of motor - 5 m				
	-S015	I/O signal cable - 1.5 m (32 Pin)				
	-S03	I/O signal cable - 3 m (32 Pin)				
	-C035 *1	Transmission cable - 3.5 m				
CM20	- ME01 *2,3	Power + Encoder cable of motor - 1 m				
	ME03 *2,3	Power + Encoder cable of motor - 3 m				
	ME05 *2,3	Power + Encoder cable of motor - 5 m				
	-S015	I/O signal cable - 1.5 m (20 Pin)				
	-S03	I/O signal cable - 3 m (20 Pin)				



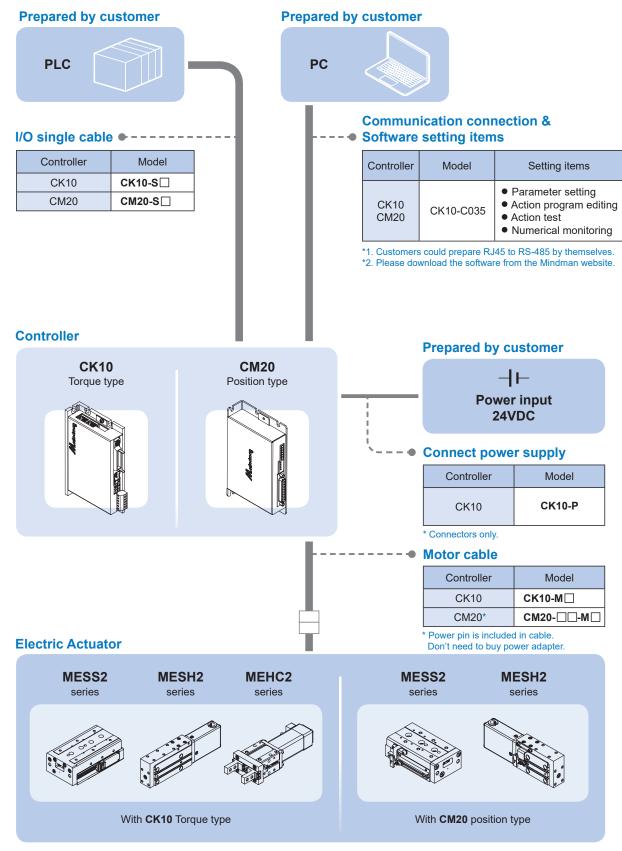
Wire material

	Wire	Material
I/O Sigr	nal cable	Isolation
Cable	Motor power cable	Flexible
	Encoder cable	Isolation + Flexible

CK10 / CM20 System structure



ELECTRIC CYLINDER CONTROLLER



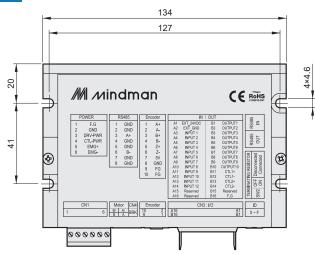
Use torque to set the origin position directly by software

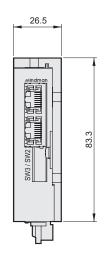
Need to install an external sensor to set the origin position (Sensor set to be purchased separately)

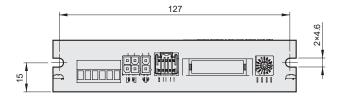




CK10







CM20

